

Auftragssteuerung einer ROS-Basierten Flotte

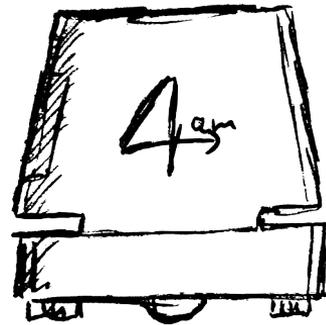
Denis Lehmann

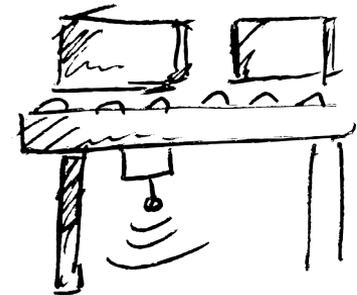
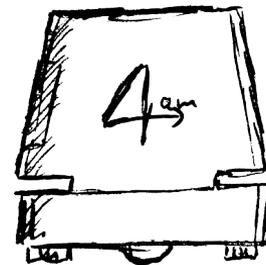
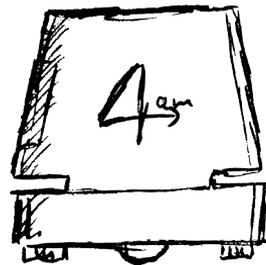
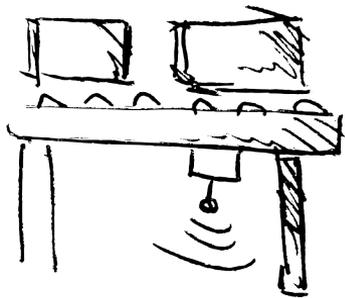
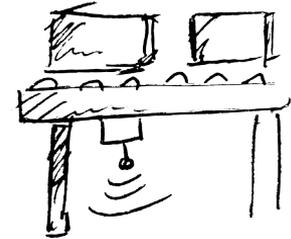
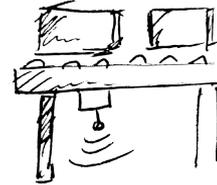
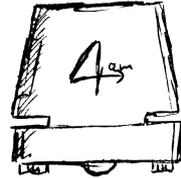
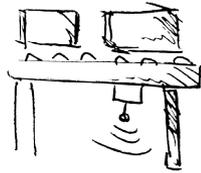
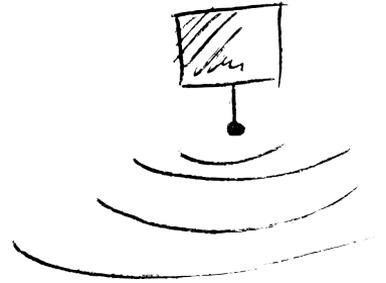
4am Robotics GmbH

ROSCon DE 2023

Karlsruhe – 24.11.2023

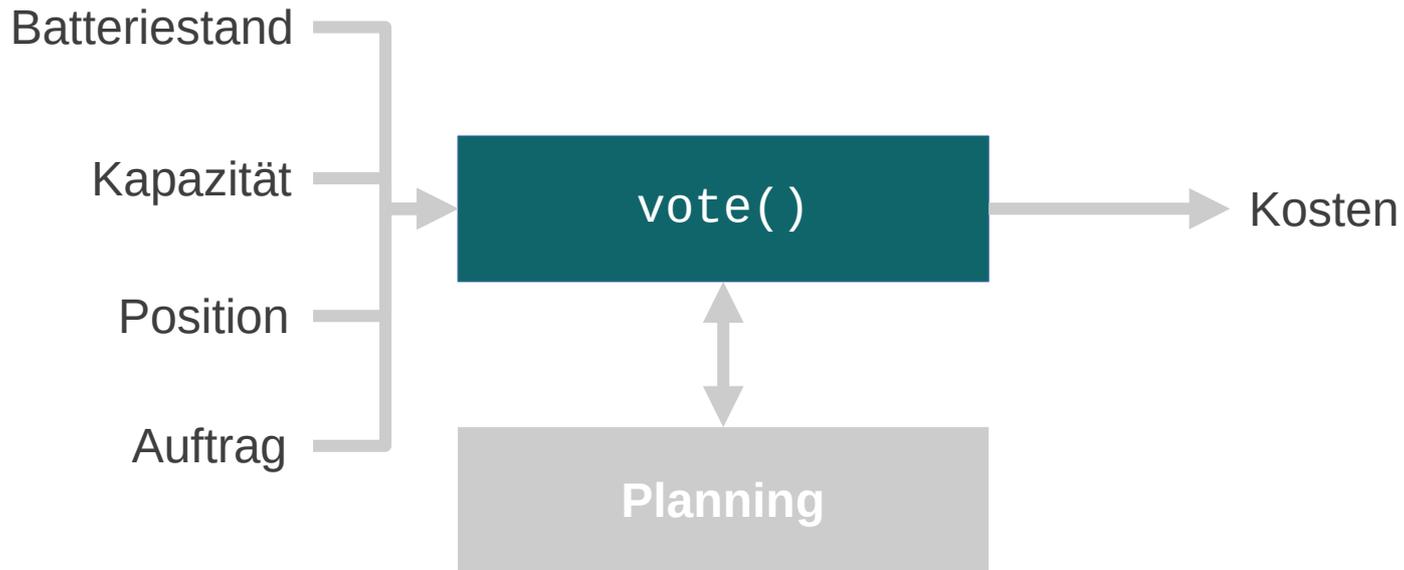


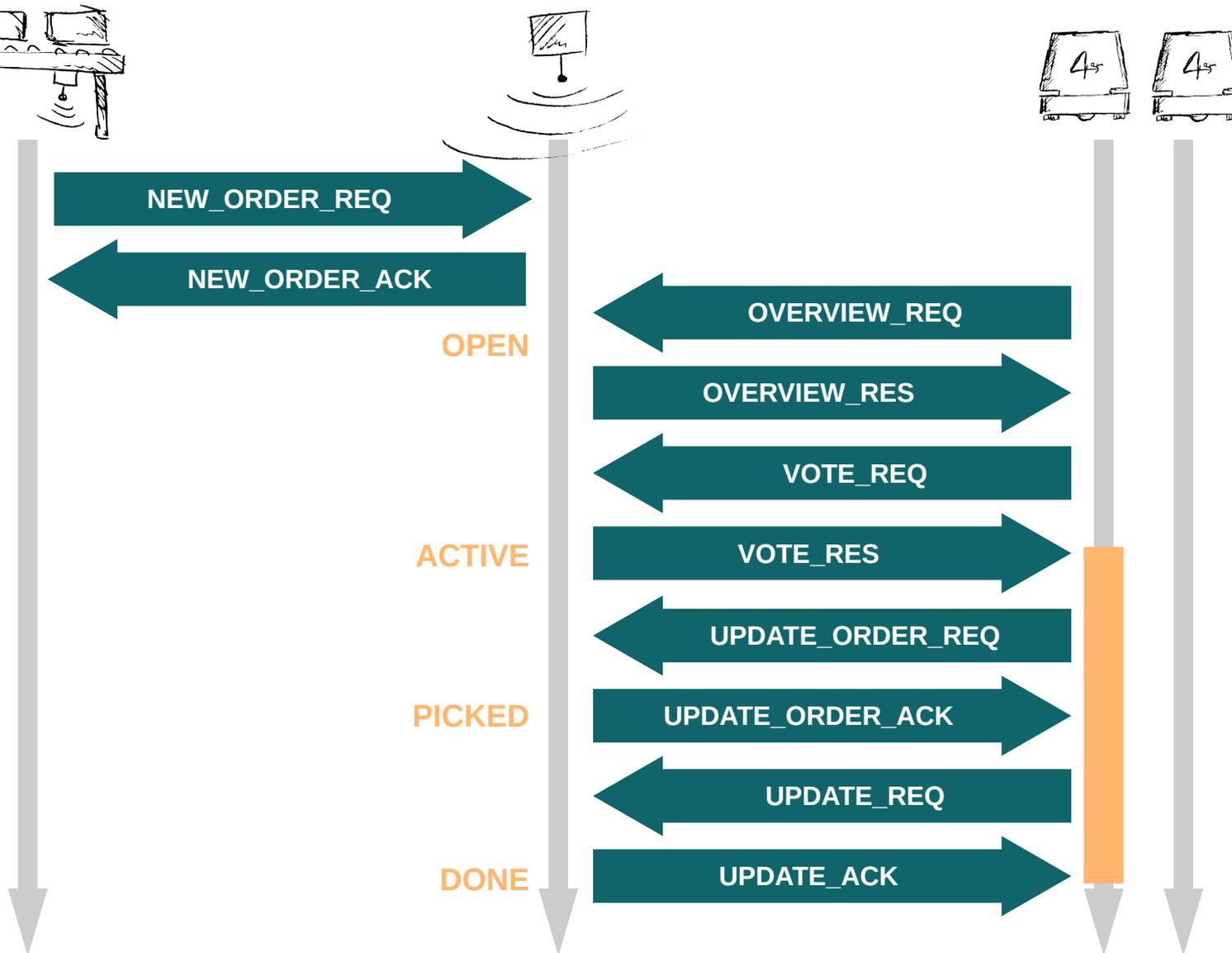


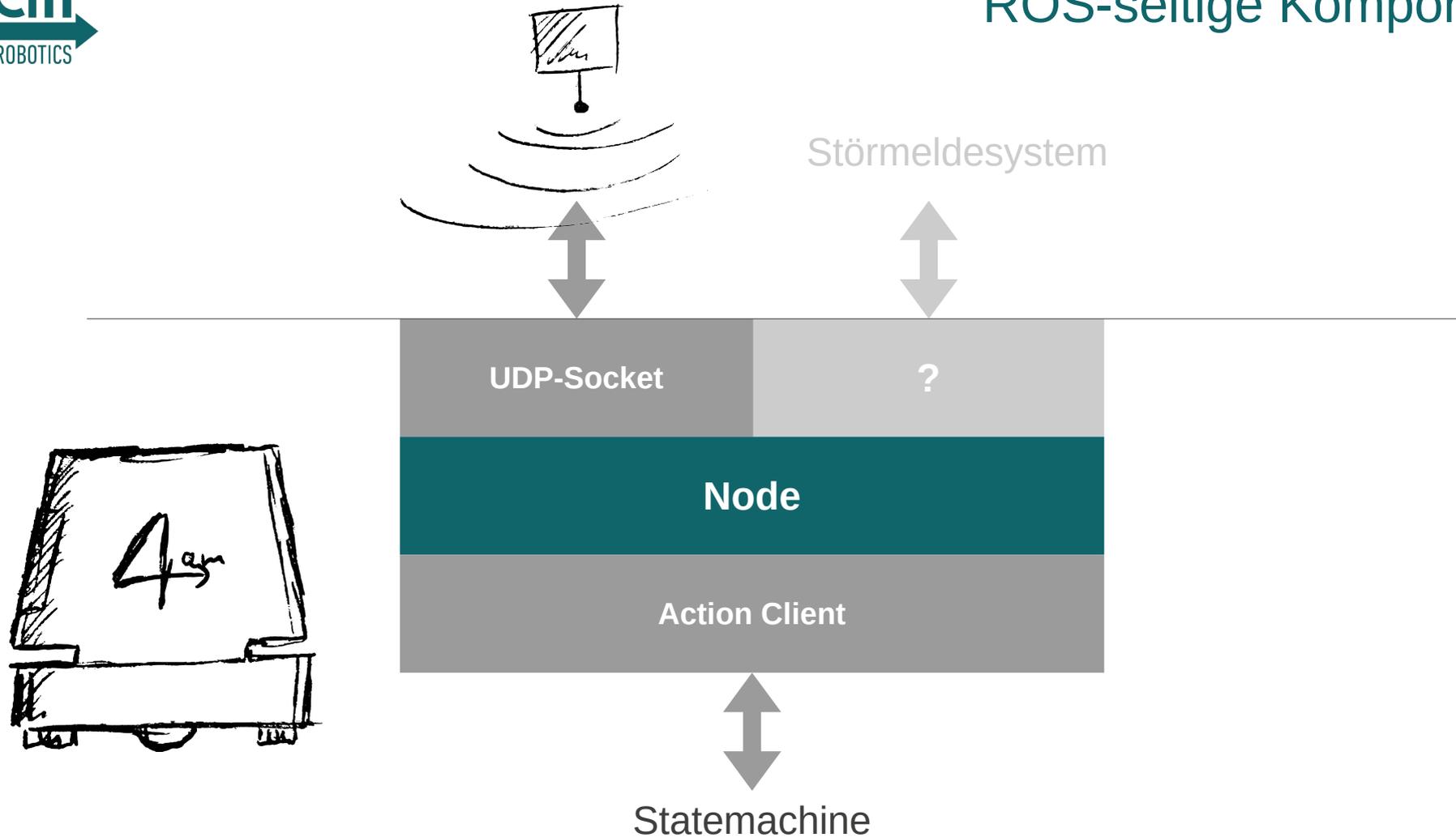


- `id`
 - Wird von der Sammelstelle vergeben
- `source_id`
- `destination_id`
- `timestamp`
- `state`
- `dependency_ids`
 - Liste an Auftrags-IDs welche zuvor abgearbeitet werden müssen







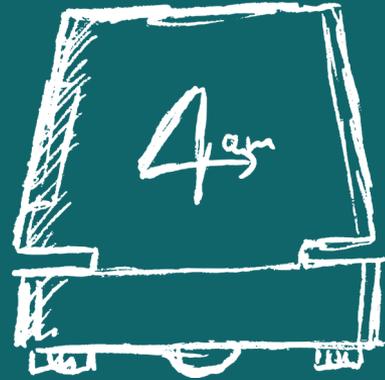
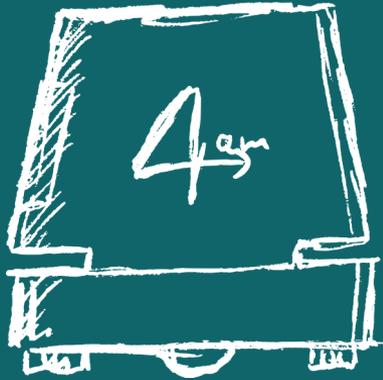


+ Einfach

+ Skalierbar



+ Intelligenz liegt bei den Robotern





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